Honeywell's HercuLine® rotary actuators feature broad torque and timing ranges, standard end-of-travel limit switches, and rugged enclosures. HercuLine® smart electric actuators are engineered for exceptional reliability, accurate positioning, and low maintenance. Designed for precise positioning of dampers and valves, they perform well in extremely demanding environments requiring continuous duty, and high reliability.

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Rather use pneumatics for valve positioning? Check out Siemens digital pneumatic positioner! See pages 352 to 353 for details.

### Fax: 630-595-2386

# sales@lesman.com

# **Comparing Rotary and Electric Actuator Motors**

# Honeywell

### Which Rotary **Actuator Is** Right for You?





| Rotary Actuators        | Modutrol IV   | HercuLine® 10260A  |
|-------------------------|---|--|
| Motor Description       | Low torque/ medium duty for non-industrially hardened applications. Lowest price/life expectancy/re-positions | Medium torque/heavy duty for industrially hardened applications. High life expectancy/ re-positions. |
| Voltage                 | 24 or 120 VAC, 1 phase  | 120 VAC, 1 phase   |
| Duty Cycle              | 25%   | Continuous (100%)  |
| Approvals/Ratings       | NEMA 3, UL, CSA, CE Mark  | NEMA 4, UL, CSA, CE Mark   |
| Gear Train              | Powered metal spur  | Steel/bronze single reduction worm   |
| Lubrication/Maintenance | Oil/None  | None   |
| Brake                   | Yes   | None required  |
| Manual Override         | Optional crank arm  | Standard handwheel, crank arm, optional handswitch   |
| Torque Range            | 35-150 lb. in.  | 10-300 lb. ft.   |
| Rotation                | 90/160°   | 90°  |
| Failsafe                | In-place/spring return  | In-place   |
| Input Signals           | 4-20 mA, 1-5 VDC, PAT, floating   | 4-20 mA, 1-5 VDC, 3-wire position proportional, on/off   |
| Deadband Adjustment     | None  | 0.2-5% of span   |
| Feedback Signals        | 135 $\Omega$ potential  | 0-20 mA, 4-20 mA, 0-5, 1-5 or 0-16 VDC, 1000 $\Omega$ , potential                                    |
| Hysteresis              | 0.60%   | <0.4% full scale   |
| Linearity               | Approximately 5%  | ± 0.25% span   |
| Mechanical Stops        | Standard, fixed   | Standard, fixed  |

## Which **Continuous Duty Electric Actuator** is Right for You?







| Electric Actuators  | HercuLine® 2000                | HercuLine® 2001/2002   | HercuLine® 10260S  |
|---------------------|--------------------------------|--|--|
| Product Description | Low torque electric actuator   | Low torque electric actuator                                       | Medium torque industrial electric actuator                         |
| Torque              | 50 to 400"-Lb ( 6 to 45 N-M)   | 50 to 400"-Lb ( 6 to 45 N-M)                                       | 100 to 300 Lb-ft ( 14 to 400 N-M)                                  |
| Stroke/Speed        | 90° to 160°/ 15 to 240 sec     | 90° to 160°/ 7.5 to 120 sec  | 90° /20/40/60 sec  |
| Input Signals       | 2 to 10 VDC, 4 to 20 mA        | 1 to 5 VDC, 4 to 20 mA floating, position proportional, open/close | 1 to 5 VDC, 4 to 20 mA floating, position proportional, open/close |
| Position Feedback   | 1000/135Ω over 90°             | 0/1 to 5 VDC, 0 to 16 VDC<br>0/4 to 20 mA, software emulation      | 0/1 to 5 VDC, 0 to 16 VDC<br>0/4 to 20 mA, software emulation      |
| Position Sensing    | Slidewire                      | 2001: Slidewire; 2002: Contactless                                 | Contactless  |
| Environmental       | -40° to 185° F (-40° to 85° C) | -40° to 170° F (-40° to 75° C)                                     | -20° to 170° F (-30° to 75° C)                                     |
| Adjustable Deadband | 0.2% to 5% span                | 2% to 5% span  | 0.2% to 5% span  |
| Options             | Local Auto/Manual Switch       | Repeatability, Local Auto/Manual Switch,<br>Local Keypad/Display   | Repeatability, Local Auto/Manual Switch,<br>Local Keypad/Display   |
| Communications      | None                           | Modbus RTU, HART®  | Modbus RTU, HART®  |

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**LOW TORQUE ACTUATORS** 

# **HercuLine™ 2000 Low Torque Precision Actuators**



- No-burnout motor can be stalled up to 100 hours without damage to the actuator
- Two end-of-travel electric limit switches are supplied as standard with all HercuLine 2000 series actuators
- Up to four additional SPDT auxiliary switches are available
- Electric handswitch with auxiliary contacts indicating an "Out-of-Auto" position is available for local electric control
- Pushrod assemblies for valve or damper connection
- Self-locking, self-releasing worm gear maintains position at loss of power. Holds >2X rated output torque
- · Manual handwheel operates the actuator when power is off
- Mount in any orientation without degrading performance
- NEMA 4X diecast aluminum industrial-grade enclosure
- · CSA, UL, CE certification

### Smart Features of the HercuLine 2001 and 2002 Models

- Alarms can be triggered from stall, temperature limit, motor cycle count, out-of-auto mode, digital input, position input failure, position sensor failure, or power up failure
- Programmable characterization, positioning and input filters
- Motor/gear train provides accurate positioning with almost instantaneous start/stop characteristics
- Optional LED display and keyboard for configuration
- Programmable auxiliary relay outputs provide indication of position, alarm status, or control of other equipment

### **Specifications**

Rotation: 90° or 150° from 0%–100% scale, limited by mechanical stops

**Position Sensing:** 2000: Dual  $1000\Omega$  film potentiometers Mechanical Stops: Factory set at 90° or 150° (±5°) adjustable

Crank Arm: Included with actuator; Adjustable, radii 1.0" to 2.8" max.; Scale: 0 to 100% full crank arm travel

Torque Setting: 88 Lb/in (10 N-m)

Output Shaft: 0.625±/-0.005" (15.88± 0.13 mm) diameter

**Local Auto/Manual Switch:** For local or automatic actuator operation Switches: Limit: Two SPDT end of travel; Auxiliary: Up to 4 SPDT switches

Input Signals: 2000: 120 VAC drive open/close; 2001/2002 Analog: 0/4 to

20 mA; 0/1 to 5, 0 to 10 VDC

**Feedback:** 2000: Dual Output  $1000\Omega$  over  $90^{\circ}$  or  $150^{\circ}$ ; 2001/2002: 0 to 20

mA, 4 to 20 mA, 0 to 5 VDC with  $250\Omega$  resistor

Operating Temperature: 2000/2001: -40° to 170° F; 2000: -40° to 185° F **Enclosure:** Precision-machined, epoxy-coated, die cast aluminum housing

**Gear Train:** Alloy steel, high efficiency steel spur gear primary train. Precision ground, self-locking/self-releasing worm gear final mesh

Mains Supply: 100-130 VAC, 60 Hz; Current: 0.4 Amp

**Communications:** Modbus RTU

Approvals: CE compliant, UL/CSA, UL Type 4 (NEMA 4X), IP66

electric actuators that incorporate all of the easy-to-use features of traditional HercuLine actuators. Designed for precise positioning of dampers and quarter-turn valves, they perform well in extreme environments that require continuous duty, high reliability, and low maintenance actuators to all parameters for painter.

maintenance decisions is standard through Modbus RTU, or local display. HercuLine 2002 have additional standard features, like non-contact position sensing and slidewire emulation output.



### **Ordering Instructions**

Make one selection from each section below. A finished catalog number looks like this: 2000-\_\_\_-\_\_\_\_

### **Model Selection Guide**

| Description  |  |   |                                     |                                     |   |        |                        | Catalog<br>Number       | Price                    |
|--|--|---|-------------------------------------|-------------------------------------|---|--------|------------------------|-------------------------|--------------------------|
| Basic Motor Unit (No Electronics) Basic Motor Unit plus Digital Electronics Enhanced Performance Motor with Non-Contact Position Sensing |  |   |                                     |                                     |   |        |                        | 2000-<br>2001-<br>2002- | \$1194.00<br>1725.00     |
| Non-Co   | miaci  |   |                                     |                                     |   |        | $\downarrow$           | 2002-                   | 2123.00                  |
| Torque and<br>Speed Sele<br>per 150° Ro  | ection   | Torque<br>100 Lb/ln<br>200 Lb/ln<br>400 Lb/ln | 50 Hz<br>15 sec<br>30 sec<br>60 sec | 60 Hz<br>12 sec<br>25 sec<br>50 sec |   | •      |                        | 100-<br>200-<br>400-    | 0.00<br>0.00<br>0.00     |
| Travel   |  | otation<br>Rotation                           |                                     |                                     | : | •      | •                      | 090-<br>150-            | 0.00<br>0.00             |
| Power  | 100 to   | 130 VAC, 60                                   | ) Hz                                |                                     | • |        |                        | 126-                    | 0.00                     |
| Analog<br>Input  | 0/40 t   | e Drive Up/D<br>to 20 mA; 0/1<br>20 mA; 0/1 t | -5, 0 to 10                         |                                     | ٠ | •      | •                      | 0<br>2<br>3             | 0.00<br>172.00<br>172.00 |
| Analog<br>Output   | None Dual $1000\Omega$ ( $100\Omega$ over $150^{\circ}$ ) Slidewire Emulation  |   |                                     |                                     |   |        | •                      | _ 00-<br>_ 15-<br>_ 60- | 0.00<br>125.00<br>244.00 |
| Auxiliary<br>Outputs   | None<br>2 Auxiliary Switches<br>4 Auxiliary Switches                           |   |                                     |                                     |   |        | •                      | 0<br>2<br>4             | 0.00<br>125.00<br>258.00 |
| Relay<br>Outputs   | None 2 Programmable Relay Outputs 4 Programmable Relay Outputs                 |   |                                     |                                     |   |        |                        | _ 0-<br>_ 2-<br>_ 4-    | 0.00<br>105.00<br>213.00 |
| Keypad/<br>Display   | None<br>Integr   | ally Mounte                                   | d Display                           |                                     | ٠ | d<br>• | d<br>•                 | 0<br>1                  | 0.00<br>305.00           |
| Auto/<br>Manual<br>Switch  | None<br>Switch with "Out of Auto Contact"<br>Switch with "Out of Auto Contact" |   |                                     |                                     |   |        |                        | _0<br>_1<br>_2          | 0.00<br>238.00<br>238.00 |
| Hand-<br>wheel   | None<br>Hand   | wheel   |                                     |                                     | • |        |                        | 00                      | 0.00<br>46.00            |
| Approvals  | UL Ty <sub>l</sub>   | oe 4/IP66, CS                                 | A                                   |                                     |   | •      | •                      | 0                       | 0.00                     |
| Shaft<br>Rotation  | Counterclockwise on Signal Increase<br>Clockwise on Signal Increase            |   |                                     |                                     |   |        |                        | 0-<br>1-                | 0.00<br>0.00             |
| Commun-<br>ications  | None<br>RS485 Modbus- Standard with EEU  |   |                                     |                                     |   |        |                        | 0-0-00<br>1-0-00        | 0.00<br>0.00             |
| Linkage<br>Assembly  |  | oint for 5/16"<br>od 18" Long,                |                                     |                                     |   |        | 52354-504<br>52354-506 | 51.75<br>88.55          |                          |

- a Not available with analog output signals. (Available only as Opt. -400-.)
- b  $135\Omega$  available by paralleling 1K potentiometer with  $158\Omega$  resistor.
- c 2001 series available with four relay outputs under future revision
- d HercuLink software, RS232/485 converter, for actuators without display.

Process Control Accessories

Pressure and Temperature Switches

**L** 336 ROTARY ACTUATORS

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## 10260A Medium Torque Rotary Actuators

# Honeywell



#### **Features**

- 100% duty cycle motor
- 10 to 300 Lb-Ft Torque High torque capability in a small package
- Accurate Positioning Motor/gear train provides accurate positioning with instantaneous start/stop characteristics
- Rugged industrial-grade enclosure
- Non-Contact Position Sensing Noncontacting sensing lowers maintenance costs
- Control Signals 4-20 mA, 1-5 VDC, position proportional control, open/close
- Output Signals 0/4-20 mA, 0/1-5 VDC (0-16 VDC), and slidewire emulation
- Low Power Consumption 120/240 VAC, 50/60 Hz, single phase  $\leq 1$  Amp

- Full Travel Speed —Full stroke travel speeds from 10 to 60 seconds (90 degrees travel, 60 Hz supply)
- Manual handwheel operates the actuator when power is not available
- Auto/Manual Electric Handswitch With auxiliary contacts indicating an "Out of Auto" position, for local electric control
- Output Shaft Hardware All 10260A actuators come with an adjustable radius and adjustable position crank arm. Optional 12" crank arm, linkage kits, and direct coupling hardware available
- Limit Switches Two end-of-travel electrical limit switches, up to four additional SPDT auxiliary switches available
- · Certified to CSA, UL, and CE

Honeywell's 10260A medium torque, industrially rated rotary actuator is engineered for exceptional reliability, accurate positioning, and low maintenance.

Designed for very precise positioning of dampers and quarter-turn valves, the 10260A performs especially well in extremely demanding environments. Typical applications include furnace pressure dampers, fuel/air ratio valves, windbox dampers, coal mine dampers, scoop tubes, and fluid gyrols.

To operate with maximum efficiency and improve process uptime, state-of-the-art control systems require accurate, responsive, and repeatable actuation of final control devices. Actuators are often overlooked when considering maintenance and ancillary support costs, yet they play an important role in system performance, and can directly impact your company's bottom line.

Honeywell 10260A actuators implement a variable inductance, non-contact position sensor mounted directly to the actuator output shaft, providing precision position sensing from 0 to 90 degrees. This technology eliminates maintenance items, such as wipers and bearings, as well as static friction, hysteresis, and electrical noise over a wide variety of demanding environmental conditions.

Honeywell slidewire emulation provides backward compatibility for three-wire position proportional control schemes while eliminating maintenance and control issues associated with slidewire wear. The slidewire emulation circuit emulates the proportional voltage output of a typical slidewire through a high-impedance circuit. The voltage output is proportional to the supply voltage and shaft position. A noncontact position sensor is used to determine shaft position in place of the slidewire.

### HercuLine® 10260S Medium Torque Smart Actuators

### **Features**

- Torque Range 10 to 300 Ft/Lbs
- Continuous Duty Cycle No-Burnout Motor: Heavy duty 72 RPM synchronous induction motor can be stalled without damage and increased current draw or temperature rise
- Full Travel Speeds: From 10-60 sec (90° travel, 60 Hz supply)
- Control Signals: 0/4 to 20 mA, 0/1 to 5 VDC, 0 to 10 VDC, digital RS485 Modbus RTU protocol, and Series 90 control
- Output Signals: 0/4 to 20 mA, 0/1 to 5 VDC, and slidewire emulation; Auxiliary outputs: SPDT switches or electromechanical relay
- Characterization: Programmable linear, equal percentage, quick opening, or user-configured 10-point characterization allows tailored control for specific applications
- Alarm Functions: Alarms can be assigned to relay outputs or accessed through Modbus

- High Accuracy: Typically 0.25% of 90° span
- Brakeless Non-Backdrive Design: Eliminates need for friction brake to prevent drift under live load or overshoot
- Local Configuration: Integral keypad and display for easy local configuration; Eliminates the need for removing covers or letting contaminants into the electronics
- RS485/Modbus RTU communication standard; HART optional



HART

### **Specifications**

**Enclosure:** Aluminum alloy casting, precision machined

Gear Train: Alloy steel, high-efficiency steel spur gear primary train with safety fused idler gear. Precision ground, self-locking/self-releasing worm gear final mesh

Mechanical Stops: Backup to CW and CCW end-of-travel limit switches to prevent over-travel

Operating Temperature: -20° to 150° F

Relative Humidity: Fully operable over 0%-99% RH noncondensing

Scale: 0% to 100% corresponding to full crank arm travel.

Crank Arm: Included with actuator. Adjustable radii, 1-7/16" to 5". Position adjustable through 360° rotation. Optional 12" crank arm adjustable 0" to 12" radii.

Output Shaft: 1" diameter, 1.5" length standard on most models. 1" diameter, 2" length standard on 10263A, 10265A, and 10269A, optional on others.

Rotation: 90° from 0% to 100% on scale, limited by mechanical stops; Fieldselectable direction via switch and jumper. Default is CCW (determined looking at the shaft)

Manual Handwheel: For positioning during power failure or setup

**Lubrication:** Teaco Starplex 2 EP grease

Fuses: Bussmann GDB1.6 (1.6 Amp fast), Littelfuse 312001 (1.0 Amp fast)

Power: 120 or 240 VAC single phase, 50 or 60 Hz

Motor: 100% duty cycle, instant start/stop, noncoasting, and nonburnout synchronous induction motor. Can be stalled up to 100 hours without damage.

Power Loss: Stavs in place

Local Auto/Manual Switch: Optional. Provides local electrical operation with "out of auto" contact for annunciation

**Motor Current:** No load = full load = locked rotor Limit Switches: Two SPDT end-of-travel limits standard

Auxiliary Switches: Optional. Up to 4 additional SPDT switches, rated 10A

@ 125 VAC, 5A @ 250 VAC

Approvals: CE compliant, CSA, UL approvals available

Bolts: Clamp: Standard arm 1-7/16-5" adjustment, optional 0-12" adjustment;Rod end: Standard and long arms 30-35 Lb/ft

### **Actuator with Motor Positioner Board**

Input (CAT/PAT Board): 4-20 mA, 1-5 VDC, 3-wire position proportional, on/off

Sensitivity: 0.20% to 5% span adjustable. Shipped at 0.5% span

Hysteresis: Less than 0.4% full scale

Linearity: ±0.25% span Repeatability: 0.20% span

Voltage/Supply Stability: 0.25% span with +10/-15% voltage change

Zero Suppression: 100% span

Input Filter: Adjustable to smooth input signal

Input Voltage: 5 VDC max.

**Output:** Two triac switches for raise-or-lower motor operation

Failsafe Operation: If input falls below 2% of span, four choices are selected by movable jumper: stop, go full upscale, go full downscale, or go to selected (adjustable) position

**Isolation:** Input is isolated from power

#### 4-20 mA Output and Slidewire Emulation

**Feedback Signals:** 0 to 20 mA, 4 to 20 mA; 0 to 5 mA, 1 to 5 mA with  $250\Omega$ resistor (0 to 16 VDC with  $800\Omega$  resistor)

Slidewire Emulation: Provides output voltage proportional to shaft position and to supply voltage (1-20 VDC) without slidewire. Emulates  $100\Omega$ to  $1000\Omega$  slidewire.

**Isolation:** Output is isolated from power and input signal

**Load Requirement:** Current output 0–1000  $\Omega$ 

### **Ordering Instructions**

Make one selection from each table section below. A finished model number looks like this: 1026\_A-\_-\_-\_-\_-

### Model Selection Guide

| Torque  | Full Travel Strokin                | ng               | Catalog | Price     |  |  |  |  |
|---|------------------------------------|------------------|---------|-----------|--|--|--|--|
| (Lb/ft)   | 50 Hz 6                            | 0 Hz             | Number  | Each      |  |  |  |  |
| 10  | 12 Sec. 10                         | O Sec.           | 10261A  | \$3174.00 |  |  |  |  |
| 20  | 24 Sec. 20                         | O Sec.           | 10262A  | 3199.00   |  |  |  |  |
| 40  |                                    | O Sec.           | 10264A  | 3191.00   |  |  |  |  |
| 60  |                                    | O Sec.           | 10266A  | 3344.00   |  |  |  |  |
| 40  |                                    | O Sec.           | 10267A  | 3563.00   |  |  |  |  |
| 80  |                                    | ) Sec.           | 10268A  | 3711.00   |  |  |  |  |
| 150   |                                    | O Sec.           | 10269A  | 5371.00   |  |  |  |  |
| 200   |                                    | O Sec.           | 10263A  | 5636.00   |  |  |  |  |
| 300   |                                    | O Sec.           | 10265A  | 6281.00   |  |  |  |  |
| Power   | Single Phase, 120 VAC, 60 Hz       |                  | -1      | 0.00      |  |  |  |  |
| Controls  | Drive Up/Down                      |                  | -0      | 0.00      |  |  |  |  |
|   | 4-20 mADC, 0-5 VDC, 1-5 VDC        | C, 1-1.25 VDC    | -1      | 824.00    |  |  |  |  |
|   | None                               |                  | -00     | 0.00      |  |  |  |  |
| Customer  | One Slidewire Emulation Out        |                  | -01     | 504.00    |  |  |  |  |
| Position  | 0/4-20 mADC; 0/1-5, 0-1.25 V       |                  | -03     | 504.00    |  |  |  |  |
| Outputs   | Dual 1000Ω (Only with Contr        |                  | -04     | 326.00    |  |  |  |  |
|   | Single $1000\Omega$ (Only with Con | itrol Opt1)      | -05     | 245.00    |  |  |  |  |
| Contact   | LS + Limit Switch                  |                  | -0      | 0.00      |  |  |  |  |
| Outputs   | LS + 2 SPDT                        |                  | -2      | 286.00    |  |  |  |  |
| (See Codes  | LS + AM                            |                  | -5      | 286.00    |  |  |  |  |
| Below)  | LS +AM +2 SPDT                     |                  | -7      | 577.00    |  |  |  |  |
| Shafts  | Standard Shaft                     |                  | -0      | 0.00      |  |  |  |  |
| Scale   | No Projecting Scale                |                  | 0       | 0.00      |  |  |  |  |
| Crank Arm   | 5" Standard Crank Arm              |                  | 0       | 0.00      |  |  |  |  |
| Rod   | None                               |                  | 0_      | 0.00      |  |  |  |  |
| Adapter   | 3/8" Rod Adapter                   |                  | 1_      | 0.00      |  |  |  |  |
| Linkage Kits  |                                    |                  | 0       | 0.00      |  |  |  |  |
| Options   | 12" to 16" Turnbuckle Kit          |                  | 1       | 205.00    |  |  |  |  |
|   | 16" to 20" Turnbuckle Kit          |                  | 2       | 205.00    |  |  |  |  |
|   | 1" Pipe Kit                        |                  | 4       | 205.00    |  |  |  |  |
| Weather-  | None                               |                  | -0      | 0.00      |  |  |  |  |
| proof   | NEMA 4/IP66                        |                  | -1      | 165.00    |  |  |  |  |
| Approval  | None                               |                  | 0_      | 0.00      |  |  |  |  |
|   | UL Listed (Good to 149° F)         |                  | 3_      | 165.00    |  |  |  |  |
| Tagging   | None                               |                  | 0       | 0.00      |  |  |  |  |
|   | Stainless Steel (Specify 3 lines   | s x 22 char ea.) | 2       | 53.00     |  |  |  |  |
| CODES: 15:1 CW/1CCW/Limit Switch 4 20 M: Motor Position 4 20 m / Innut: CODE. |                                    |                  |         |           |  |  |  |  |

CODES: LS: 1 CW/1 CCW Limit Switch, 4-20 IN: Motor Position 4-20 mA Input; SPDT: Aux. SPDT Switch, AM: Auto-Manual Switch with Out-of-Auto Contact

### Actuator Motor Linkage Analysis Software

- arm radius, linkage length, and transmitted torque through full travel of the driven shaft
- Displays torque and link force curves through full travel
- Suggests the right actuator for each linkage application
- Displays data in printable table
- Computes arm radius or load Point, Click, Specify, and Size!
  - Save linkage design and installation time and materials
  - Size and specify actuators
  - Change linkage arrangement quickly and easily
  - Displays positive valve and damper shutoff data



### **Model Selection Guide**

| Description                                 | Cat. Number  | Price    |
|---|--------------|----------|
| Honeywell Industrial Motor Actuation and    |              |          |
| Linkage Analysis Software for Windows (HAL) | 51197910-001 | \$138.00 |

**L** 338 ROTARY ACTUATORS

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# **Modutrol IV Low-Torque Rotary Actuator Motors**

Low torque, light duty, rotary action Modutrol IV motor is designed for accurate positioning of dampers and valves in industrial ovens, furnaces, and process heaters.

More models available online. Visit <a href="https://www.Lesman.com/get/modutrol.php">www.Lesman.com/get/modutrol.php</a> for full specs and model selection guides.

 $\textbf{Limit Switches:} \ \mathsf{Two} \ \mathsf{end}\text{-}\mathsf{of}\text{-}\mathsf{travel} \ \mathsf{limit} \ \mathsf{switches} \ \mathsf{standard}$ 

**Torque Rating**: 25 to 300 Lb-In **Approvals:** CSA, UL





### **Model Selection Guide**

| Stroke<br>90°  | Timing<br>  160°  | Torque<br>Rating  | Auxiliary<br>Switches           | Product Includes  | Functional Replacement<br>for These Obsolete Models   | Catalog<br>Number  | Price  |
|--|---|---|---------------------------------|---|---|--|--|
| Proportio  | onal-Reve   | rsing Motors  | s, 24 VAC Pov                   | wer, 135 Ohm Input Signal, 90° to 160° l  | Field-Adjustable Stroke (Unless otherwise specific  | ed)  |  |
| 15 sec<br>15 sec<br>30 sec   | 30 sec<br>30 sec<br>60 sec  | 75 Lb-in<br>75 Lb-in<br>60 Lb-in  | 0<br>1<br>0*                    | Tapped Shaft<br>24 VAC, Spring Return   | M9484D1002, D1036, and E1116<br>M7285A1052, M7282A1006,   | M9184D1005<br>M9484E1009<br>M9185D1004   | \$982.49<br>1283.74<br>1136.45   |
| 30 sec<br>30 sec<br>30 sec<br>30 sec   | 60 sec<br>60 sec<br>60 sec<br>60 sec                                | 60 Lb-in<br>75 Lb-in<br>150 Lb-in<br>150 Lb-in  | 1<br>1<br>0<br>0*               | Transformer   | M9175D1014, D1006, and D1014  M9484D1028, D1044, and D1051  M9184A1012, A1035, B1009, B1017, B1025,  M9184D1013, D1047, and D4009  M9484E1090 and E4003 | M9185E1019<br>M9174B1027<br>M9484D1010<br>M9184D1021<br>M9484E1017                                     | 1259.87<br>997.07<br>1077.59<br>1019.56  |
| 30 sec<br>30 sec<br>30 sec<br>30 sec<br>30 sec<br>60 sec                     | 60 sec<br>60 sec<br>60 sec<br>60 sec<br>—<br>60 sec                 | 150 Lb-in<br>150 Lb-in<br>150 Lb-in<br>150 Lb-in<br>35 Lb-in<br>60 Lb-in              | 1<br>2<br>2<br>2<br>2<br>2      | Motor Crank Arm,<br>Ships in 90° Position<br>Ships in 90° Position<br>Tapped Shaft, Ships in 90° Position | M9484E1025, E1041, E1058, E1066,<br>M9484E1074, and E1082<br>M9184F1000 and F1018   | M9484E1033<br>M9484F1007<br>M9484F1031<br>M9184F1034<br>M9184C1031<br>M9185A1018                       | 1269.08<br>1328.40<br>1362.84<br>1229.26<br>1022.11<br>1158.72                       |
| _  | 60 sec<br>60 sec  | 60 Lb-in<br>150 Lb-in   | 2<br>0                          | 24 VAC, Spring Return<br>wer, 135 Ohm Input Signal, 90° to 160°   | M9181A1012, M9184A1001 Field-Adjustable Stroke (Unless otherwise specif   | M9185C1006<br>M9184A1019   | 1175.38<br>982.49  |
| 30 sec<br>30 sec<br>30 sec   | 60 sec<br>60 sec<br>60 sec  | 35 Lb-in<br>35 Lb-in<br>75 Lb-in  | 0<br>0*<br>2                    | Adjustable Zero/ Span, Transformer  Transformer   | M8161A1024 and A1032,<br>M9161A1008, M9164A1021 and A1054<br>M9164A1120, A1062, A1047, and A1096  | M9164A1005<br>M9164D1009<br>■ M9174C1025   | 854.08<br>741.19<br>1087.88  |
| Proportion 15 sec  | onal-Reve<br>30 sec   | rsing Motors<br>75 Lb-in  | s, 120 VAC Po<br>0              | wer, Modulating 4-20 mA Input, Adjust   | able Zero and Span. Transformer and Screw Term  | inal Adapter Include<br>M7284A1038   | d<br>1110.19   |
| 30 sec<br>30 sec<br>30 sec<br>30 sec<br>60 sec<br>30 sec<br>30 sec<br>30 sec | 60 sec<br>60 sec<br>60 sec<br>120 sec<br>60 sec<br>60 sec<br>60 sec | 150 Lb-in<br>150 Lb-in<br>150 Lb-in<br>150 Lb-in<br>300 Lb-in<br>60 Lb-in<br>60 Lb-in | 0<br>0<br>2<br>2<br>2<br>0<br>2 | Spring Return<br>Spring Return<br>Spring Return   | M281A1007, M7284A1046<br>M7284A1020<br>M7284C1018, M7284C1026<br>M7284Q1017   | M7284A1004<br>M7284A1012  M7284C1000  M7284Q1009<br>M7294Q1007  M7285A1003<br>M7285C1009<br>M7285Q1008 | 1066.05<br>1098.03<br>1249.91<br>1337.41<br>1106.72<br>1245.20<br>1414.16<br>1513.16 |
| Proportio  | onal-Reve   | rsing Motors  | s, 24 VAC Pow                   | ver, Modulating 4-20 mA Input, Transfor   | mer Included. Enhanced Resolution Models, Min   | imum 160 Positions   | per Swing.   |
| 30 sec   | <br>60 sec  | 150 Lb-in<br>150 Lb-in  | 2 2                             |   | M7284C1059<br>M7284C1067  | M7284C1083<br>M7284C1091   | 1280.02<br>1347.92   |
| Motors v   | vith Switcl<br>30 sec   | 75 Lb-in  | Floating Out<br>0               | put, 120 VAC Power, SPDT Input, 3-Wire  | , Line Voltage, or Position Proportional Controlle  | r<br>M6184A1023  | 790.08   |
| 30 sec   | with Switch   | 150 Lb-in<br>ned SPDT or  | 0<br>Floating Out               | put, 24 VAC Power, 3-Wire, SPDT or Volt   | M6284A1014, A1002, A1048, A1071, and 1063   | M6284A1055-S   | 880.77   |
| 15 sec<br>30 sec   | 30 sec<br>60 sec  | 75 Lb-in<br>150 Lb-in   | 0<br>0*                         | Low Voltage<br>Low Voltage<br>Low Voltage   | M6181A1018, D1004, F1009, F1017,<br>M6161A1004, M6184A1007 and B1021  | M6184D1001<br>M6184D1035   | 676.10<br>715.53   |
| 30 sec   | 60 sec  | 150 Lb-in   | 2                               | Line Voltage  |   | M6184F1014   | 904.25   |

| Stroke  | Stroke | Torque   | Auxiliary |                  | Functional Replacement                   | Catalog      |          |
|---|--------|----------|-----------|------------------|--|--------------|----------|
| Timing  | (Deg)  | Rating   | Switches  | Product Includes | for These Obsolete Models                | Number       | Price    |
| Two-Position Spring Return Motors, SPST, 2-Wire, Voltage Inputs |        |          |           |                  |  |              |          |
| 30 sec  | 75°    | 20 Lb-in | 1         | 120 VAC Power    | M436A1041 A1082, A1090, A1165, and A1181 | M436A1116    | \$453.36 |
| 30 sec  | 75°    | 20 Lb-in | 1         | 240 VAC Power    |  | M436A1124    | 470.77   |
| 60 sec  | 160°   | 60 Lb-in | 0         | 120 VAC Power    |  | M4185A1001   | 656.45   |
| 60 sec  | 160°   | 60 Lb-in | 1         | 120 VAC Power    | M4182B1002                               | ■ M4185B1009 | 695.63   |
| 30 sec  | 90°    | 60 Lb-in | 1         | 120/208/240 VAC  | M4185B1017                               | ■ M4185B1058 | 743.70   |
| 30/60   | 90/160 | 60 Lb-in | 0*        | 24 VAC           | M8185B1000 and B1034 (w/ 220736A)        | M8185D1006   | 579.45   |

<sup>\*</sup> Field-addable auxiliary switches