# DCP552B Mark II <br> DIGITRONIK ${ }^{\text {TM }}$ <br> Programmable Controller 

## Overview

The DIGITRONIK ${ }^{\text {TM }}$ DCP552B Mark II is a high-function programmable controller supporting two channels (up to 49 program patterns per channel) to which thermocouple, resistance temperature detector (RTD), DC voltage, DC current and other signals can be input.
The DCP552 Mark II supports 16 event outputs, 16 external switch inputs and a wide range of other functions as part of the standard specification.

## Features

- Accuracy of $\pm 0.1 \%$ FS. Easy-to-view large display characters. Compact design.
- Any input type can be selected by console key operation.
- Easy operation aided by guidance messages.
- Up to 49 program patterns can be stored to each channel and up to 99 segments can be programmed to each pattern.
- Any event can be selected to each channel and set for the 16 event outputs, and code events comprising a combination of two or more points can be set.

- 16 external switch inputs allow the control of remote selection of program Nos. or operation on each channel separately or both channels simultaneously.
- CE marking-compatible

Applicable standards: EN61010-1, EN61326

Basic function blocks of DCP552B Mark II


Specifications

| Program | Number of programs | 49 programs $\times 2$ channels |
| :---: | :---: | :---: |
|  | Number of segments | 99 per program, total 2000 |
|  | Segment setting system | RAMP-X: Set by set points (SP) and time <br> RAMP-T: Set by set points (SP) and ramp ( $\theta$ ) <br> RAMP-E: Set by set points (SP) and $\triangle$ SP per external switch input 1 pulse |
|  | Segment time | 0 to 500 hours 0 minute, 0 to 500 minutes 0 second, 0.0 to 3000.0 seconds (time unit selectable) |
|  | Segment ramp | 1 to $10000 \mathrm{U} /$ hour, 1 to $10000 \mathrm{U} /$ minute, 1 to $10000 \mathrm{U} /$ second (time unit selectable) |
|  | Segment $\triangle$ SP | 1 to 10000 U/1 pulse |
|  | Number of subfunctions | 4000 |
|  | Sub-function action | Events, PID set, output limiter set, G.Soak, PV shift, repeat |
|  | Events (16) | Set operating point corresponding to event type |
|  | PID set No. | Set 0 (continuation of previous segment), 1 to 9 , A set (automatically switched) and ON-OFF control |
|  | Output limiter set | Set 0 (continuation of previous segment), 1 to 9 |
|  | G.Soak | Set type (start/end points and overall) and G. Soak width 0 to 1000 U. |
|  | PV shift | -10000 to +10000 U |
|  | Repeat | Set return destination segment No. and repeat count. |
|  | PV start | Set type (rising/falling or both) for each program. |
|  | Cycle | Set cycle count for each program. |
|  | Pattern link | Set program No. 0 to 49 (0: no link) for each program. |
|  | Tag | Set 8 alphanumerics or symbols for each program. |
|  | Basic time accuracy | $\pm 0.01 \%$ (segment time setting $=0$, with 0.1 second delay for each repeat and cycle) |
| Inputs | Input type | Thermocouple, resistance temperature detector (RTD), DC voltage, DC current multi-range (See pages 6, 7.) |
|  | Sampling cycle | 0.1 seconds |
|  | Input bias current | Thermocouple, DC voltage input: Max. $\pm 1.3 \mu \mathrm{~A}$ (at peak value and reference conditions) <br> 1 V or higher range: Max. $-3 \mu \mathrm{~A}$ |
|  | Input impedance | DC current input: approx. $50 \Omega$ (under operating conditions) |
|  | Measuring current | RTD input: Approx. 1 mA current flow from terminal A (under operating conditions) |
|  | Influence of wiring resistance | Thermocouple, DC voltage input: Thermocouple: $0.5 \mu \mathrm{~V} / \Omega$ <br>  DC voltage (max. 1 V range) $: 0.5 \mu \mathrm{~V} / \Omega$  <br>  DC voltage ( 5 V range): $3 \mu \mathrm{~V} / \Omega$ <br>  DC voltage (10 V range): $6 \mu \mathrm{~V} / \Omega$ <br> RTD input: $M a x . ~$ $0.01 \% \mathrm{FS} / \Omega$ in wiring resistance range 0 to $10 \Omega$  <br> Range of F01, F33, P01 and P33: $\pm 0.02 \% \mathrm{FS} / \Omega$ max..   |
|  | RTD input allowable wiring resistance | - Ranges other than F01, F33, P01 and P33: $85 \Omega$ max. <br> - Ranges of F01, F33, P01 and P33: $10 \Omega$ max. |
|  | Allowable parallel resistance | Thermocouple disconnection detection allowable parallel resistance: $1 \mathrm{M} \Omega \mathrm{min}$. |
|  | Max. allowable input | Thermocouple, DC voltage input: -5 to +15 V DC DC current input: 50 mA DC, 2.5V DC |
|  | Burnout | Detection selectable |
|  | Over-range detection threshold | 110\%FS min.: Upscaled <br> -10\%FS max.: Downscaled (Note that F50 range is not downscaled.) |
|  | Cold-junction compensation accuracy | $\pm 0.5^{\circ} \mathrm{C}$ (under standard conditions) |
|  | Cold- junction compensation system | Internal/external ( $0^{\circ} \mathrm{C}$ only) compensation selectable |
|  | Scaling | -19999 to +20000 U (possible in case of linear input only. Inverse scaling possible. Decimal point position settable at any point) |
|  | Square root extraction | Possible. Dropout: 0.2 to $10.0 \%$ in case of DC current or DC voltage range |
|  | PV equalizer (linearization table approximation) | PV1: 9 segments (10 points set) <br> PV2: 9 segments (10 points set) <br> CP: 9 segments (10 points set) |
|  | Input bias | -1000 to +1000 U variable |
|  | Digital filter | 0.0 to 120.0 seconds variable (0.0: filter OFF) |


| External switch inputs | Number of inputs | 16 |  |
| :---: | :---: | :---: | :---: |
|  | Types of connectable outputs | Dry contacts (relay contact) and open-collector (current sink to ground) |  |
|  | Terminal voltage (open) | $8.5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ between common terminals (terminals (12), (40)) and each input terminal (under operating conditions) |  |
|  | Terminal current (short-circuit) | Approx. 6 mA between each terminal (under operating conditions) |  |
|  | Allowable contact resistance (dry contact) | ON: $250 \Omega$ max. (under operating conditions) OFF: $100 \mathrm{k} \Omega \mathrm{min}$. (under operating conditions) |  |
|  | Voltage drop (at open-collector ON) | 2 V max. (under operating conditions) |  |
|  | Leakage current (at open-collector OFF) | 0.1 mA max. (under operating conditions) |  |
|  | Parallel connection with other instruments | Can be connected to Azbil Corporation SDC40 and SDC10 series |  |
|  | Assignments (fixed) | RUN, HOLD, RESET, ADV, program No., CH 1 operation cancel, CH 2 operation cancel |  |
|  | Assignments (variable) | RAMP-E, FAST, AT, AUTO/MANUAL, G.Soak cancel, auto-load, $\mathrm{O}_{2}$ sensor check |  |
|  | Input sampling cycle | 0.1 seconds |  |
|  | ON detection min. hold time | 0.2 seconds ( 0.4 seconds for program No.) |  |
| Indication/ programmer | Upper display | Green 5-digit, 7-segment LED <br> This displays PV values in the basic display state. Item codes are displayed in the parameter setup. |  |
|  | Lower display | Orange 5-digit, 7-segment LED <br> This displays SP and output \% in the basic display state. Setting values are displayed in the parameter setup. |  |
|  | Program No. display | Green 2-digit, 7-segment LED <br> This displays program No. in the basic display state. |  |
|  | Segment No. display | Green 2-digit, 7-segment LED <br> This displays segment No. in the basic display state. <br> Item Nos. are displayed in parameter setup, and alarm No. is displayed when alarm occurs. |  |
|  | Message display | This displays output graph, deviation graph, event state and tags in the basic display state. This displays reference messages in the parameter setup and program setup. This displays operation details and operation results of memory card operation. |  |
|  | Profile display | 7 orange LEDs Displays program pattern rise, soak and fall trends. |  |
|  | Status displays | ```22 round LEDs Modes: RUN, HLD, MAN, PRG (green) Display details: PV, SP, OUT, TM, CYC, SYN, DEV (green), EG1, EG2 (red) Battery voltage: BAT (red) (blinks at low voltage) Status: AT (green)``` |  |
|  | Operation keys | 18 rubber keys |  |
|  | Loader connector port | 1 (dedicated cable with stereo miniplugs) |  |
| Modes | Program operation modes | READY: Ready to run program (control stop/program No. selectable) <br> RUN: Program run <br> HOLD: Program hold <br> FAST: Program fast-forward <br> END: Program end <br> READY FAST: Ready to run and fast-forward program |  |
|  |  | AUTO: Automatic operation <br> MANUAL: Manual operation (output can be controlled on console) |  |
|  | Constant-value operation modes | READY: Ready to run program (control stop) <br> RUN: Program run <br> AUT:  |  |
|  |  | AUTO: Automatic operation <br> MANUAL: Manual operation (output can be controlled on console) |  |
| Controller | PID controls | Proportional band (P) | 0.0 to 1000.0\% (0.0: ON-OFF control) |
|  |  | Reset time (I) | 0 to 3600 seconds. 0 seconds: PD control |
|  |  | Rate time (D) | 0 to 1200 seconds. 0 seconds: PI control |
|  |  | MV limit | Lower limit: -5.0 to upper limit \% Upper limit: Lower limit to $+105.0 \%$ |
|  |  | Manual reset | 0.0 to 100.0\% |


| Controller | PID controls | Number of PID sets | 16 sets for program operation ( 9 segment unique sets +7 sets for automatic zone selection) |
| :---: | :---: | :---: | :---: |
|  |  | PID set selection | Segment designation/automatic zone selection can be switched by program operation. |
|  |  | MV change | 0.1 to 110.0\%/0.1 seconds |
|  |  | Auto-tuning | Automatic setting of PID value by limit cycle system |
|  |  | ON-OFF control differential | 0 to 1000 U |
|  | Direct/reverse action switching | Possible |  |
| Outputs | Auxiliary output | Output types | SP1, PV1, deviation 1, MV1, SP2, PV2, deviation 2, $\mathrm{O}_{2}$ sensor mV value |
|  |  | Scaling | Possible |
|  | Current output (5G) CH1, CH2 auxiliary outputs CH1, CH2 | Output current: 4 to 20 mA DC <br> Allowable load resistance: $600 \Omega$ max. (under operating conditions)  <br> Output accuracy: $\pm 0.1 \%$ FS max. (under standard conditions) <br> Output resolution: $1 / 10000$ <br> Max. output current: 21.6 mADC <br> Min. output current: 2.4 mA DC <br> Output updating cycle: 0.1 seconds <br> Open terminal voltage: 25 V max. |  |
|  | Voltage output (6D) CH1, CH2 | Allowable load resistance: $600 \Omega$ max. (under operating conditions) <br> Load current adjustment: 2 to 22 mA variable <br> Variable open terminal voltage: 25 V max. <br> OFF leakage current: $\quad 100 \mu \mathrm{~A}$ max. <br> Output response time: At ON-OFF $600 \Omega$ load: 0.5 ms max. <br> Output resolution: $\quad 1 / 1000$ <br> Time-proportional cycle: 1 to 240 seconds variable |  |
|  | Open-collector output (8D) $\mathrm{CH} 1, \mathrm{CH} 2$ | External supply voltage: 12 to 24 V DC <br> Max. load current: $100 \mathrm{~mA} / \mathrm{load}$ <br> OFF leakage current: 0.1 mA max. <br> ON residual voltage: 2 V max. <br> Output resolution: $1 / 1000$ <br> Time-proportional cycle: 1 to 240 seconds variable |  |
| Event outputs | Open-collector output | External supply voltage: 12 to 24 V DC <br> Max. load current: $70 \mathrm{~mA} / \mathrm{load}$ <br> Max. common current: 500 mA <br> OFF leakage current: 0.1 mA max. <br> ON residual voltage: 2 V max. |  |
|  | Event types | PV type | PV, deviation, w/ deviation standby, absolute value deviation, w/ absolute value deviation standby, PV rate-of-change, SP, MV, G.Soak absolute value deviation, w/ G.Soak absolute value deviation standby, PV1 constant operation, PV2 constant operation |
|  |  | Time type | Time events, RAMP-E time monitor, segment time, program time |
|  |  | Code type | Code event, code event w/ timer, program No. binary code, segment No. binary code, program No. BCD code, segment No. BCD code |
|  |  | Mode type | Unique segment, RUN+HOLD+END+FAST, HOLD, READY+READY FAST, END, G.Soak standby, MANUAL, AT executing, FAST+READY FAST, console operation in progress, RUN, advance, all alarms, PV range alarm, controller alarm, $\mathrm{O}_{2}$ sensor error, low battery voltage |
|  | Event hysteresis | In case of PV type set, 0 to 1000 U |  |
|  | Event ON delay | 0.0 to 3000.0 can be set to four events |  |
| Communications | RS-485 | Network | Multidrop <br> This controller is provided with only slave instrument functionality except when connected to ST221 (dedicated display device). <br> 1 to 16 units max. (DIM) <br> 1 to 31 units max. (CMA, SCM) |
|  |  | Data flow | Half duplex |
|  |  | Synchronization | Start-stop synchronization |
|  |  | Transmission system | Balanced (differential) |
|  |  | Data line | Bit serial |
|  |  | Signal line | 5 transmit/receive lines (3-wire connection also possible) |
|  |  | Transmission speed | 1200, 2400, 4800, 9600 bps |
|  |  | Transmission distance | 500 m max. (total) <br> ( 300 m max. for MA500 DIM connection) |
|  |  | Other | Conforming to RS-485 interface specifications |


| Communications | RS-485 | Char. bit count | 11 bits/character |
| :---: | :---: | :---: | :---: |
|  |  | Format | 1 start bit, even parity, 1 stop bit; or 1 start bit, no parity, and 2 stop bits |
|  |  | Data length | 8 bits |
|  |  | Isolation | All inputs and outputs are completely isolated except external switch inputs. |
|  | RS-485 communications can be performed by connecting to a computer equipped with an RS-485 interface or to Azbil Corporation MX200, MA500 (DK link II DIM) or CMA50 controllers. |  |  |
|  | RS-232C | Network | 1:1 Connected, This controller is provided with only slave instrument functionality. |
|  |  | Data flow | Half duplex |
|  |  | Synchronization | Start-stop synchronization |
|  |  | Transmission system | Unbalanced type |
|  |  | Data line | Bit serial |
|  |  | Signal line | 3 transmit/receive lines |
|  |  | Transmission speed | 1200, 2400, 4800, 9600 bps |
|  |  | Transmission distance | 15 m max. |
|  |  | Other | Conforming to RS-232C interface specifications |
|  |  | Char. bit count | 11 bits/character |
|  |  | Format | 1 start bit, even parity, 1 stop bit; or 1 start bit, no parity, and 2 stop bits |
|  |  | Data length | 8 bits |
|  |  | Isolation | All inputs and outputs are completely isolated except external switch inputs. |
| General specifications | Memory backup | Memory: Battery backed up RAM <br> Battery life: Controller power OFF: Approx. 5 years under standard conditions Controller power ON: Approx. 10 years under standard conditions |  |
|  | Rated power voltage | 100 to 240 V AC, $50 / 60 \mathrm{~Hz}$ |  |
|  | Power consumption | 40 VA max. |  |
|  | Power ON rush current | 50 A max. |  |
|  | Power ON operation | Reset time: 10 seconds max. (time until normal operation is possible under normal operating conditions) |  |
|  | Allowable transient power loss | 20 ms max. (under operating conditions) |  |
|  | Insulation resistance | Min. $50 \mathrm{M} \Omega$ across power terminal (39) or (40) and FG terminal (52) or (53) (by 500V DC megger) |  |
|  | Dielectric strength | 1500 V AC $50 / 60 \mathrm{~Hz}$ for 1 minute between power terminal and FG terminal <br> Note) The primary side and secondary side capacities are joined inside the product. For this reason, when carrying out a withstand voltage test, disconnect the wiring of the grounded secondary side terminals (e.g. when grounding type thermocouple is used) from that terminal. If the test is carried out with the wiring as it is, this might result in malfunction. |  |
|  | Standard conditions | Ambient temperature | $23 \pm 2^{\circ} \mathrm{C}$ |
|  |  | Ambient humidity | $60 \pm 5 \% \mathrm{RH}$ |
|  |  | Rated power voltage | 105 V AC $\pm 1 \%$ |
|  |  | Power frequency | $50 \pm 1 \mathrm{~Hz}$, or $60 \pm 1 \mathrm{~Hz}$ |
|  |  | Vibration resistance | $0 \mathrm{~m} / \mathrm{s}^{2}$ |
|  |  | Shock resistance | $0 \mathrm{~m} / \mathrm{s}^{2}$ |
|  |  | Mounting angle | Reference plane (vertical) $\pm 3^{\circ}$ |


| General specifications | Operating conditions | Ambient temperature range | 0 to $50^{\circ} \mathrm{C}$ (ambient temperature at the bottom side of case when gang-mounted) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Ambient humidity range | 10 to $90 \% \mathrm{RH}$ (condensation not allowed) |  |  |  |  |
|  |  | Rated power voltage | 100 to 240 V AC |  |  |  |  |
|  |  | Allowable power voltage | 90 to 264V AC |  |  |  |  |
|  |  | Power frequency | $50 \pm 2 \mathrm{~Hz}$, or $60 \pm 2 \mathrm{~Hz}$ |  |  |  |  |
|  |  | Vibration resistance | 0 to $1.96 \mathrm{~m} / \mathrm{s}^{2}$ |  |  |  |  |
|  |  | Shock resistance | 0 to $9.80 \mathrm{~m} / \mathrm{s}^{2}$ |  |  |  |  |
|  |  | Mounting angle | Reference plane (vertical) $\pm 10^{\circ}$ |  |  |  |  |
|  | Transport/storage conditions | Ambient temperature range | -20 to $+70^{\circ} \mathrm{C}$ |  |  |  |  |
|  |  | Ambient humidity range | 10 to $95 \%$ RH (condensation not allowed) |  |  |  |  |
|  |  | Vibration resistance | 0 to $4.90 \mathrm{~m} / \mathrm{s}^{2}$ ( 10 to 60 Hz for 2 hours each in $\mathrm{X}, \mathrm{Y}$ and Z directions) |  |  |  |  |
|  |  | Shock resistance | 0 to $490 \mathrm{~m} / \mathrm{s}^{2}$ (3 times vertically) |  |  |  |  |
|  |  | Package drop test | Drop height: 60 cm (1 angle, 3 edges and 6 planes; free fall) |  |  |  |  |
|  | Terminal screw | M3.5 self-tapping screws |  |  |  |  |  |
|  | Terminal screw tightening torque | 0.78 to $0.98 \mathrm{~N} \cdot \mathrm{~m}$ |  |  |  |  |  |
|  | Mask/case materials | Mask: Multilon |  | Case: Multilon |  |  |  |
|  | Mask/case color | Mask: Dark gray (Munsell 5Y3.5/1) Case: Light gray (Munsell 2.5Y7.5/1) |  |  |  |  |  |
|  | Installation | Specially designed mounting bracket |  |  |  |  |  |
|  | Weight | Approx. 1.5 kg |  |  |  |  |  |
| Standard accessories | Item | Model No. | Q'ty | Auxiliary parts (sold separately) | Item | Model No. | Q'ty |
|  | Unit indicating label | - | 1 |  | Lithium battery set | 81446140-001 | Approx. 200 g |
|  | Mounting bracket | 81446044-001 | 1 set (2 p'ces) |  |  |  |  |
|  | User's manual | CP-UM-5017E | 1 |  |  |  |  |
|  | Terminal cover | 81446176-001 | 1 |  |  |  |  |

Table 1 Input types and ranges (selectable in setup)

- Thermocouple

| Input type |  |  | Input range (FS) |  | Accuracy (under standard conditions) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | Code | Range No. | ${ }^{\circ} \mathrm{C}$ | ${ }^{\circ} \mathrm{F}$ |  |  |
| K (CA) | K46 | 16 | -200.0 to +200.0 | -300.0 to +400.0 | $\pm 0.1 \%$ FS |  |
| K (CA) | K09 | 0 | 0.0 to 1200.0 | 0 to 2400 | $\pm 0.1 \%$ FS |  |
| K (CA) | K08 | 1 | 0.0 to 800.0 | 0 to 1600 | $\pm 0.1 \%$ FS |  |
| K (CA) | K04 | 2 | 0.0 to 400.0 | 0 to 750 | $\pm 0.1 \%$ FS |  |
| E (CRC) | E08 | 3 | 0.0 to 800.0 | 0 to 1800 | $\pm 0.1 \%$ FS |  |
| $J$ (IC) | J08 | 4 | 0.0 to 800.0 | 0.0 to 1600 | $\pm 0.1 \%$ FS |  |
| T (CC) | T44 | 5 | -200.0 to +300.0 | -300 to +700 | $\pm 0.1 \%$ FS | $\pm 0.3 \%$ FS between $-200^{\circ} \mathrm{C}$ to $-45^{\circ} \mathrm{C}$ |
| B (PR30-6) | B18 | 6 | 0.0 to 1800.0 | 0 to 3300 | $\pm 0.1 \%$ FS | $\pm 4.0 \%$ FS between 0 to $260^{\circ} \mathrm{C}$, $\pm 0.15 \%$ FS between 260 to $800^{\circ} \mathrm{C}$ |
| R (PR13) | R16 | 7 | 0.0 to 1600.0 | 0 to 3100 | $\pm 0.1 \%$ FS |  |
| S (PR10) | S16 | 8 | 0.0 to 1600.0 | 0 to 3100 | $\pm 0.1 \%$ FS |  |
| W (WRe5-26) | W23 | 9 | 0.0 to 2300.0 | 0 to 4200 | $\pm 0.1 \%$ FS |  |
| W (WRe5-26) | W14 | 10 | 0.0 to 1400.0 | 0 to 2552 | $\pm 0.1 \%$ FS |  |
| PR40-20 | D19 | 11 | 0.0 to 1900.0 | 0 to 3400 | $\pm 0.2 \%$ FS | $\pm 0.9 \%$ FS between 0 to $300^{\circ} \mathrm{C}$, <br> $\pm 0.5 \% \mathrm{FS}$ between 300 to $800^{\circ} \mathrm{C}$ |
| N | U13 | 12 | 0.0 to 1300.0 | 32 to 2372 | $\pm 0.1 \%$ FS |  |
| PLII | Y13 | 13 | 0.0 to 1300.0 | 32 to 2372 | $\pm 0.1 \%$ FS |  |
| Ni -Ni-Mo | Z13 | 14 | 0.0 to 1300.0 | 32 to 2372 | $\pm 0.1 \%$ FS |  |
| Golden iron chromel | Z06 | 15 | 0.0 to 300.0 K (K: Kelvin) |  | $\pm 0.4 \%$ FS |  |

Thermocouple: K, E, J, T, B, R, S (JIS C 1602-1981)
WRe5-26 (Hoskins Data)
PR40-20 (Johnson Matthey Data)
N (N.B.S. Monograph 161)
PLII (Engelhard Industries Data (IPTS68))
Ni-NiMo (General Electric Data)
Gold iron chromel (Hayashidenko Data)

- Resistance temperature detector (RTD)

| Input type |  |  | Input range (FS) |  | Accuracy (under standard conditions) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | Code | Range No. | ${ }^{\circ} \mathrm{C}$ | ${ }^{\circ} \mathrm{F}$ |  |  |
| JIS'89Pt100 <br> (IEC Pt100 $\Omega$ ) | F50 | 64 | -200.0 to +500.0 | -300.0 to +900.0 | $\pm 0.1 \%$ FS |  |
|  | F46 | 65 | -200.0 to +200.0 | -300.0 to +400.0 | $\pm 0.1 \%$ FS |  |
|  | F32 | 66 | -100.0 to +150.0 | -150.0 to +300.0 | $\pm 0.1 \%$ FS |  |
|  | F36 | 67 | -50.0 to +200.0 | -50.0 to +400.0 | $\pm 0.1 \%$ FS |  |
|  | F33 | 68 | -40.0 to +60.0 | -40.0 to +140.0 | $\pm 0.15 \%$ FS |  |
|  | F01 | 69 | 0.0 to 100.0 | 0.0 to 200.0 | $\pm 0.15 \%$ FS |  |
|  | F03 | 70 | 0.0 to 300.0 | 0.0 to 500.0 | $\pm 0.1 \%$ FS |  |
|  | F05 | 71 | 0.0 to 500.0 | 0.0 to 900.0 | $\pm 0.1 \%$ FS |  |
| JIS'89JPt100 | P50 | 96 | -200.0 to +500.0 | -300.0 to +900.0 | $\pm 0.1 \%$ FS |  |
|  | P46 | 97 | -200.0 to +200.0 | -300.0 to +400.0 | $\pm 0.1 \%$ FS |  |
|  | P32 | 98 | -100.0 to +150.0 | -150.0 to +300.0 | $\pm 0.1 \%$ FS |  |
|  | P36 | 99 | -50.0 to +200.0 | -50.0 to +400.0 | $\pm 0.1 \%$ FS |  |
|  | P33 | 100 | -40.0 to +60.0 | -40.0 to +140.0 | $\pm 0.15 \%$ FS |  |
|  | P01 | 101 | 0.0 to 100.0 | 0.0 to 200.0 | $\pm 0.15 \%$ FS |  |
|  | P03 | 102 | 0.0 to 300.0 | 0.0 to 500.0 | $\pm 0.1 \%$ FS |  |
|  | P05 | 103 | 0.0 to 500.0 | 0.0 to 900.0 | $\pm 0.1 \%$ FS |  |

Resistance temperature detector (RTD): Pt100, JPt100 (JIS C 1604-1989)

- DC current, DC voltage

| Input type |  |  | Input range (FS) |  | Accuracy (under standard conditions) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | Code | Range No. |  |  |  |  |
| mA (linear) | C01 | 48 | 4 to 20 mA | Programmable range $-19999 \text { to }+20000$ <br> (decimal point position can be changed) | $\pm 0.1 \%$ FS |  |
|  | Z51 | 52 | 2.4 to 20 mA |  | $\pm 0.1 \%$ FS |  |
| mV (linear) | M01 | 49 | 0 to 10 mV |  | $\pm 0.1 \%$ FS |  |
|  | L02 | 50 | -10 to +10 mV |  | $\pm 0.1 \%$ FS |  |
|  | - | 51 | 0 to 100 mV |  | $\pm 0.15 \%$ FS |  |
| mA (linear) | C01 | 128 | 4 to 20 mA | Programmable range -19999 to +20000 <br> (decimal point position can be changed) | $\pm 0.15 \%$ FS |  |
|  | Z51 | 134 | 2.4 to 20 mA |  | $\pm 0.1 \%$ FS |  |
| V (linear) | - | 129 | 0 to 1 V |  | $\pm 0.1 \%$ FS |  |
|  | - | 130 | -1 to +1 V |  | $\pm 0.1 \%$ FS |  |
|  | V01 | 131 | 1 to 5 V |  | $\pm 0.1 \%$ FS |  |
|  | - | 132 | 0 to 5 V |  | $\pm 0.1 \%$ FS |  |
|  | - | 133 | 0 to 10 V |  | $\pm 0.1 \%$ FS |  |
| $\mathrm{O}_{2}$ sensor * | - | 135 | 0 to 1250 mV <br> Carbon potential (CP value) indication range: $0.000 \text { to } 4.000 \% \mathrm{C}$ <br> (Note that PID control is calculated in input range 0.000 to $2.000 \%$ C.) <br> $\mathrm{O}_{2}$ partial pressure $\left(\mathrm{PO}_{2}\right)$ indication range: 0.000 to $1.500 \times 10^{-20} \mathrm{~atm}$ |  | $\pm 0.1 \%$ FS | When converted to mV value |

* • Any $\mathrm{O}_{2}$ sensor made by Japan Glass Co., Ltd., Marathon Monitors, Cambridge, Corning, AACC (Advanced Atmosphere Control Corporation), Barber Colman and Furnace Control can be used.
- PV2 is fixed for the $\mathrm{O}_{2}$ sensor in the case of models supporting carbon potential.


## ! Handling Precautions

- The unit of code Z06 is Kelvin (K).
- The PV lower limit alarm does not occur with codes F50 and P50.
- The number of digits past the decimal point for $D C$ current and $D C$ voltage is programmable within the range 0 to 4 .
- The PV upper limit alarm is output by the $\mathrm{O}_{2}$ sensor when the voltage exceeds 1375 mV . The PV lower limit alarm, however, is not output.


## Model selection guide



## External dimensions

(Unit: mm)


## Panel cutout

(Unit: mm)


## Wiring



## - Input

- PV input CH1

- PV input CH2



## Note:

If voltage mode signals are input to PV input CH1 (terminal Nos. (55), (56) and input CH2 (terminal Nos. (58), (59) for current input by mistake, a large current might flow and cause the controller to malfunction. Before wiring to the current input terminals on the DCP552B, make sure that current input signals are output correctly within the range 4 to 20 mA .

## - Control output and auxiliary output

- Control output

Current output
CH1 control output (current output)


Open collector output

CH1 control output (voltage output)


CH2 control output (current output)


## Voltage output



- Auxiliary output




## - Communications I/O (option)

RS-485 3-wire type


RS-232C
(DCP552B)



RS-485 5-wire type

Note (1) In the case of a modem type connected master instrument, connect terminals 2 and 61, and 3 and 63 in reverse to the above figure.
(2) The RS-232C terminals 4-5 and 6-8-20 on the computer must be short-circuited as shown in the figure on the left.
(3) In the case of a computer whose RS-232C terminals 1 and 7 are for the same signal, do not connect the leads as shown in the above figure. Also, do not connect the sleeve marked "FG" to any terminal at all.

## Wiring precautions

## 1. Isolating inputs and outputs inside the controller

Solid lines _ show isolated items.
Dotted lines -------- show non-isolated items.

| PV input CH 1 | Digital circuit | Control output CH1 |
| :---: | :---: | :---: |
| PV input CH 2 |  | Auxiliary output CH 1 |
| Loader communications |  | Control output CH2 |
| External switch input |  | Auxiliary output CH2 |
| Communications |  | Event output |

## 2. Noise countermeasures for Instrument power supplies

(1) Reducing noise

Connect the DCP552B to a single-phase power supply for instruments, and take measures to prevent the influence of electrical noise.

(2) When there is a lot of noise

If there is a lot of electrical noise, we recommend inserting an insulating transformer in the power circuit and using a line filter.


## 3. Noise generating sources and countermeasures

Generally, the following generate electrical noise:
Relays and contacts, electromagnetic coils, solenoid valves, power lines (in particular, 90 V AC min.), induction loads, inverters, motor commutators, phase angle control SCR, radio communications equipment, welding equipment, high-voltage ignition equipment
(1) Fast-rising noise

CR filters are effective in countering fast-rising noise.
Recommended CR filter:
Azbil Corporation Model No. 81446365-001
(2) Noise with a high wave height

Varisters are effective in countering noise with a high wave height. However, note that the varister may become short-circuited when trouble occurs. Pay attention to this when providing a varister on a controller.
Recommended varister:
Azbil Corporation Model No.
81446366-001 (for 100V AC)
81446367-001 (for 200V AC)

## 4. Ground

Use only the FG terminal (52) or (53) on the DCP552B for grounding. Do not ground across other terminals. When it is difficult to ground shielded cable, prepare a separate GND terminal plate (earth bar).
Ground type: $100 \Omega$ max.
Ground cable: $2 \mathrm{~mm}^{2} \mathrm{~min}$. annealed-copper wire (AWG14)
Cable length: Max. 20 m


## 5. Precautions during wiring

(1) After providing anti-noise measures, do not bundle primary and secondary power leads together, or pass them through the same piping or wiring duct.
(2) Maintain a distance of at least 50 cm between I/O signal leads or communications leads and the power lead. Also, do not pass these leads through the same piping or wiring duct.

## 6. Inspection after wiring

After wiring is completed, be sure to inspect and check the wiring state. Wrong wiring may cause controller malfunction or accidents.

Please, read 'Terms and Conditions' from following URL before the order and use.
http://www.azbil.com/products/bi/order.html

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