

Touchpoint Pro Gas Detection System



REVISIONS

Revision History

Revision	Comment	Date
Issue 1	A04948	Jan 2017



LEGAL NOTICES

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In no event shall Honeywell be liable for any damages or injury of any nature or kind, no matter how caused, that arise from the use of the equipment referred to in this manual.

Strict compliance with the safety procedures set out and referred to in this manual, and extreme care in the use of the equipment, are essential to avoid or minimise the chance of personal injury or damage to the equipment.

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This warranty does not cover consumables, batteries, fuses, normal wear and tear, or damage caused by accident, abuse, improper installation, unauthorized use, modification or repair, ambient environment, poisons, contaminants or abnormal operating conditions.

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This is a summary. For full warranty terms please refer to the Honeywell Analytics' General Statement of Limited Product Warranty, which is available on request.

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1 Introduction

This Touchpoint Pro Safety Manual contains information, tables, examples and instructions to assist readers to install, commission and perform maintenance that ensure the ongoing safety of the Touchpoint Pro gas detection system.

This manual may be used to calculate the probability of Touchpoint Pro system or component failure (PFD/PFH) for use in risk assessments and other scenarios.

1.1 References

IEC 61508: Functional Safety of Electrical/Electronic/Programmable Electronic Safety-related Systems (E/E/PE, or E/E/PES)

IEC 61508 has seven parts:

- Parts 1-3 contain the requirements of the standard (normative)
- Parts 4-7 are guidelines and examples for development and are thus informative.

Central to the standard are the concepts of risk and safety function. Risk is a function of the likely frequency of the hazardous event and the likely consequence and severity of an event. The risk can be reduced to a tolerable level by applying safety functions that may consist of E/E/PES and/or other technologies. While other technologies may be employed in reducing the risk, only those safety functions relying on E/E/PES are covered by the detailed requirements of *IEC 61508*.

2400M2501 Touchpoint Pro Technical Handbook.

This manual contains all of the TPPR specifications, approvals, certifications and core technical information. It is intended for use by authorised technical personnel and OEMs, and is available in Technical English only.

2400M2566 Touchpoint Pro Operating Manual.

This manual is an abridged and translated version of the TPPR Technical Handbook. It is intended for use by end users and operators.



1.2 Abbreviations

The following abbreviations have been used in this manual:

- AC Alternating CurrentAIM Analogue Input Module
- $\bullet \hspace{0.5cm} \beta \hspace{1.5cm} \text{Beta Factor} \text{Common Cause Failure Factor for } \underline{\text{Undetected}} \hspace{0.1cm} \text{Dangerous Failures}$
- β_D Beta Factor Common Cause Failure Factor for <u>Detected</u> Dangerous Failures
- CCB Control Centre Board (Touchpoint Pro)
- COB Communications Board (Touchpoint Pro)
- DC Direct Current
- D_D <u>Detected</u> Dangerous Failures
- DIM Digital Input Module
- Du <u>Undetected</u> Dangerous Failures
- I/O Input/Output
- LED Light Emitting Diode
- mA MilliampmV Millivolt
- NC Normally Closed (circuit)
- NO Normally Open (circuit)
- PFD Probability of failure to perform its design function on demand
- PFD_{avg} Probability of failure to perform its design function on demand (Averaged)
- PFH Probability of a dangerous failure per hour
- POST Power On Self-TestPSU Power Supply Unit
- ROM Relay Output Module
- SD Secure Digital (memory card)
- SFF Safe Failure Fraction; a percentage of safe failures as compared to all failures
- SIL Safety Integrity Level
- SIS Safety Instrumented Systems
- SPCO Single Pole Change Over (Switch or Relay)
- TPPR Touchpoint Pro Gas Detection System
- UI User Interface
- UPS Uninterruptible Power Supply
- USB Universal Serial Bus



1.3 **Definitions**

Mean Time to Restoration The average time for failures of the device to be repaired or otherwise fixed.

Proof Test A test procedure undertaken to ascertain that the product is operating in an "as new" condition.

the PFD figure.



SAFETY PARAMETERS

2 Touchpoint Pro Safety Parameters

Module	PFD Value	PFH Value	SFF	Diagnostic Coverage	β	β _D	D _D	Dυ	Safe
4-20mA Input Module	1.91 _* 10 ⁻⁰⁴	4.10 _* 10 ⁻⁰⁸	97%	96%	2%	1%	1427.11	40.98	460.08
mV Input Module	1.621*10 ⁻⁰⁴	3.41 _* 10 ⁻⁰⁸	98%	97%	2%	1%	1800.34	34.12	236.54
Digital Input Module	2.20*10 ⁻⁰⁴	4.78*10 ⁻⁰⁸	95%	94%	2%	1%	1446.12	47.78	196.52
Relay Output Module (Complex)	1.48*10 ⁻⁰⁴	3.20 _* 10 ⁻⁰⁸	97%	94%	2%	1%	1045.18	31.96	315.13
Relay Output Module (Simple)	5.53*10 ⁻⁰⁴	1.26÷10 ⁻⁰⁷	54%	11%	2%	1%	15.40	126.05	134.98
Control Module (Complex)	3.08*10 ⁻⁰⁴	6.58*10 ⁻⁰⁸	98%	91%	2%	1%	2256.51	64.66	1144.59
Control Module (Simple)	1.13*10 ⁻⁰⁵	2.64*10 ⁻⁰⁹	55%	18%	2%	1%	54.20	242.82	241.65

NOTE: Relay Module figures appear twice in the table above. The "complex" entry indicates the common complex portion of the module. The "simple" entry shows the effect of the simple relay contact portion of the module. This approach allows the user to determine the effect of using multiple relay contacts (which is required to attain a SIL 2 level for a safety chain). Using only one relay contact will allow the user to construct a SIL 1 safety chain.

NOTE: Control Module figures appear twice in the table above. The "complex" entry indicates the common complex portion of the module. The "simple" entry shows the effect of the relay outputs for the System Fault and System Fail relays. The "simple" entry values only need to be added to evaluate any safety chain that contains the control module relay outputs (System Fail or System Fault Relay contacts).

The PFD figures quoted above assume a nominal one-year proof test interval and 8-hours mean time to restoration.

Common cause analysis has been undertaken for the Relay contacts (shown above in the "Relay Output Module (Simple)" row). This allows us to give PFD and PFH figures for the use of two relay contacts wired together (see also section 2.2.4 for further information) for differing proof test intervals (as it is seen to be a complex procedure for the user to test his output contacts). A similar calculation has been undertaken for the system fail and system fault relays on the control module (although in this case the two relays are wired together internally).

	Relay Output Module		Control Module Relays		
Proof Test Interval	PFD Value	PFH Value	PFD Value	PFH Value	
6 Months	5.64×10 ⁻⁰⁶	2.59 _* 10 ⁻⁰⁹	5.59 _* 10 ⁻⁰⁶	2.58 _* 10 ⁻⁰⁹	
1 Year	1.15 _* 10 ⁻⁰⁵	2.66*10 ⁻⁰⁹	1.13 _* 10 ⁻⁰⁵	2.64*10 ⁻⁰⁹	
2 Years	2.37×10 ⁻⁰⁵	2.79 _* 10 ⁻⁰⁹	2.34*10 ⁻⁰⁵	2.77*10 ⁻⁰⁹	
3 Years	3.67×10 ⁻⁰⁵	2.92 _* 10 ⁻⁰⁹	3.62*10 ⁻⁰⁵	2.89 _* 10 ⁻⁰⁹	
4 Years	5.05*10 ⁻⁰⁵	3.06*10 ⁻⁰⁹	5*10 ⁻⁰⁵	3×10 ⁻⁰⁹	
5 Years	6.50×10 ⁻⁰⁵	3.19 _* 10 ⁻⁰⁹	6.4×10 ⁻⁰⁵	3.14×10 ⁻⁰⁹	
7 Years	9.65×10 ⁻⁰⁵	3.46*10 ⁻⁰⁹	9.45*10 ⁻⁰⁵	3.4×10 ⁻⁰⁹	
10 Years	1.50×10 ⁻⁰⁴	3.86×10 ⁻⁰⁹	1.46*10 ⁻⁰⁴	3.76 _* 10 ⁻⁰⁹	



2.1 Proof Test Interval

The purpose of a proof test is to return the unit to an 'as new' condition in terms of its safety parameters.

The nominal proof test interval is 12 calendar months but, as stated in IEC 61508 and always dependent on local conditions, users may vary the proof test interval to meet their system needs. Honeywell allows such variations provided that the proper calculation method for calculating a proof test interval —as defined in IEC 61508 — is used to attain the required SIL level.

Proof test variations will depend on the system, hardware architectures and applications, and should be reviewed annually.

Given that relay outputs could be complex to isolate and test, the user may determine that a longer proof test interval would be desirable. The table given in section 2 provides the different PFD & PFH values for these differing proof test intervals.

Note: The nominal proof test interval should not preclude more frequent maintenance of Touchpoint Pro in accordance with the Operating Instructions if site conditions or other factors require it.



2.2 Special Conditions for Safety Compliance

2.2.1 General / System Conditions

- Specification of the Touchpoint Pro system must be carried out using the Honeywell provided power calculator (refer to your Honeywell service representative to obtain this tool). This is to ensure that temperature rise and power dissipation remains within expected and previously observed limits.
- 2. The notes in the Technical Handbook for installation, operation and maintenance have to be considered.
- 3. Power Supply Fluctuations are not to exceed DC 18 32 V Supply or ±10 % of nominal. A SELV / PELV power supply should be used.
- 4. All equipment in this manual is rated to 2000 m (6562 ft.) altitude maximum.
- 5. All rack-mounted enclosures are Equipment Class 1 (grounded) and Installation Category 2.
- 6. Touchpoint Pro may be the primary or only alarm system in use. Always ensure that risk is identified and alternative arrangements are put in place before carrying out any proof testing, bump testing, or sensor calibrations.
- The TPPR product performs a full diagnostic self-check every 30 seconds. Hence, in the unlikely event that a fault
 occurs immediately after the diagnostic has just completed, the indication of this fault could be delayed by up to 30
 seconds.
- 8. The end user must satisfy themselves that the Touchpoint Pro product meets the needs of the targeted safety application. Overall safety validation remains the responsibility of the end user.

2.2.2 Modification Conditions

- 1. After any modification to the product configuration a verification shall be completed by testing the functionality (a sub-set of the relevant proof tests detailed in section 3.2 can be used to accomplish this)
- 2. After any firmware or software update to the product a verification shall be completed by testing the functionality and configuration (a sub-set of the relevant proof tests detailed in section 3.2 can be used to accomplish this)

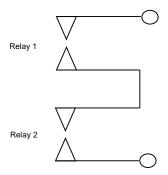
2.2.3 System Input Conditions

- 1. Any oxygen sensors connected to the product must have both a positive and negative alarm associated with them.
- 2. All digital inputs used for a safety function must be used in fully supervised mode.
- 3. Digital inputs used as inputs to a safety chain must be configured so that in normal (non-alarm) conditions the switch / input is closed.
- 4. Digital inputs used for interaction purposes (inhibit, reset) must be configured so that in normal conditions the switch / input is open.
- 5. Sensor cables must be protected from mechanical damage [e. g. by using armoured cable].

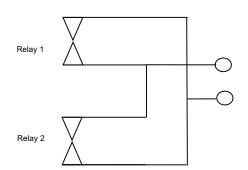


2.2.4 Relay Output Conditions

- 1. Touchpoint Pro contains relays that may be used to perform executive actions when an alarm is triggered. Ensure that such systems are identified and inhibited / disconnected before carrying out any proof testing, bump testing, or sensor calibrations.
- Users are expected to configure the cause and effect rules so that all outputs transition to the safe state when a fault is
 present on the associated inputs. For some specific outputs this may not be desirable hence it is possible to disable this
 option. In such cases the user is expected to pay close attention to the state of the entire system in the case that a
 system fault is indicated.
- 3. The System Fail and System Fault relay outputs are rated for SIL 2 operation.
- 4. The relay contacts must be protected with a fuse rated at a maximum of 3A. This applies both to the relay contacts from the control module (System Fail and System Fault relays), and the relay contacts from the Relay output modules when used in Configuration 1 as shown in the figure below.
- The relay output module relays must be energised under normal conditions.
- 6. Use of one relay contact from a relay output module will allow a SIL 1 rated output to be realised.
- 7. To realise a SIL 2 rated output, it is mandatory to wire two relay contacts of a relay module together. One of the two configurations shown below can be used. Configuration 1 should be used when an "open contact" represents the activation of the safety function whereas Configuration 2 should be used when a "closed contact" represents the activation of the safety function. Configuration 1 requires the addition of a protective fuse rated at a maximum of 3A to protect the relay contacts from adverse events which may cause contact welding.



Normally Open Contacts (as labelled on the module) Configuration 1



Normally Closed Contacts (as labelled on the module) Configuration 2



3 Proof Tests

It is recommended that users carry out routine maintenance procedures before carrying out more specific proof tests.

It is recommended that the TPPR system or parts thereof be taken off-line to carry out proof testing in order to avoid false alarms or signalling. Always ensure that a risk assessment is carried out and alternative safety arrangements are put in place during testing.

Remote Units do not include a Controller but still require proof testing of all other components.

The proof tests detailed below use the inbuilt test facilities (test modes) provided by the TPPR controller.

When a test mode is active the **System Fault** relay will normally open and a **Test Mode Fault** will be shown as an **Active Event** on the User Interface, which cannot be reset. The exceptions are the LED Panel Test and LCD screen, which do not indicate a fault.

Once a test mode is active, the system will remain in test mode until the test is exited. The only exception is in the case of a power cycle of the TPPR, when it will restart in normal mode.

Note: After 20 minutes of inactivity the system will logout and return to the **System Status** screen. However it is still running in test mode and you will need to login to complete the tests.

All events generated while the system is in test mode will be logged in the event history.

3.1 Controller Proof Tests

Three main elements should be periodically tested as a part of the HMI controller (LED Panel, Panel Buttons, LCD Screen). The testing for these three elements are detailed in the sub-sections below:

3.1.1 LED Panel Test

Engineer access level is required.

The purpose of this test is to check that the LEDs on the panel are working correctly. This test does not indicate a Fault while in progress.

How to use the LED Panel Test mode:

- 1. Login as an Engineer.
- 2. From the **System Status** screen select the **Tool Box** icon:



- 3. Select Diagnostics.
- 4. Select the **Menu** icon:
- 5. Select LED Panel Test.
- 6. The system will ask you to confirm, select **OK** to proceed.
- 7. The system will illuminate all LEDs and then cycle through the LEDs turning each one on in turn. Note: The green power LED will remain illuminated throughout if it is working correctly.
- 8. At the end of the test the system will ask you to confirm the LED test passed.



3.1.2 Panel Button Test

Engineer access level is required.

The purpose of this test is to check that the buttons on the panel are working correctly.

How to use the Panel Button Test mode:

- 1. Login as an Engineer.
- 2. From the **System Status** screen select the **Tool Box** icon:



3. Select Diagnostics.

- 4. Select the Menu icon: 🚾
- 5. Select Panel Button Test.
- 6. The system will ask you to confirm, select Yes to proceed.
- 7. The system will confirm you are in panel button test mode. Press **OK** to proceed.
- 8. Follow the on-screen prompts to test the panel buttons
- 9. At the end of the test the system will display the test results
- 10. Press **OK**.
- 11. Select the Menu icon:



- 12. Select Stop panel Button Test.
- 13. The system will show a confirmation message that it has returned to normal operation.

3.1.3 LCD Screen Test

Engineer access level is required.

The purpose of this test is to check that the LCD screen is working correctly. This test does not indicate a Fault while in progress.

How to use the LCD Screen Test mode:

- 1. Login as an Engineer.
- 2. From the **System Status** screen select the **Tool Box** icon:



- 3. Select Diagnostics.
- 4. Select the **Menu** icon:
- 5. Select LCD Screen Test.
- 6. The system will display a series of coloured bars and a progress bar.
- 7. When the progress bar completes the system asks you to confirm the bars were visible
- 8. Then select **Yes** if the bars were visible and **No** if the screen appears abnormal.



3.2 CCB Proof Tests

The purpose of the Control Centre Board tests are to ensure that the controller holds the correct configuration, executes the expected cause and effect rules and has a fully operational System Fault and System Fail relay output. Tests for each of these areas is detailed in the sub-sections below:

3.2.1 System Relay Test

Engineer access level is required.

The purpose of this test is to check that the System Failure and System Fault relays are working correctly. A multimeter or similar test instrument should be used to check the state of the contacts at various points through the proof test.

Note: It may be necessary to disconnect wiring to higher level systems from TB4 (System Failure) and TB5 (System Fault) on the TPPR controller. This test may cause higher level systems to activate if connected.

How to use the System Relay Test mode:

- 1. Login as an Engineer.
- 2. From the **System Status** screen select the **Tool Box** icon:



- 3. Select Diagnostics.
- 4. Select the **Menu** icon:
- Select System Relay Test.
- 6. The system will ask you to confirm, select **Yes** to proceed.
- 7. The system will confirm you are in relay test mode. Press OK to proceed.
- 8. The system will operate the System Fail relay and ask the user to confirm the monitoring applied by the engineer has indicated that the relay has been activated (contacts closed).
- 9. The system will operate the System Fail relay and ask the user to confirm the monitoring applied by the engineer has indicated that the relay has been deactivated (contacts permanently open with no state switching).
 - Note: The System Fail relay will be toggling during this test to ensure that no contacts have welded
- 10. The system will operate the System Fault relay and ask the user to confirm the monitoring applied by the engineer has indicated that the relay has been activated (contacts closed).
- 11. The system will operate the System Fault relay and ask the user to confirm the monitoring applied by the engineer has indicated that the relay has been deactivated (contacts permanently open with no state switching).

Note: The System Fault relay will be toggling during this test to ensure that no contacts have welded.

- 12. At the end of the test the system will display the test results.
- 13. Press OK.
- 14. Select the Menu icon:



- 15. Select Stop System Relay Test.
- 16. The system will show a confirmation message that it has returned to normal operation.
- 17. Reconnect TB4 and TB5 if necessary.



3.2.2 **Configuration Settings Test**

This proof test should be run following initial commissioning, after the required periodic interval as well as after any modification to the configured rules (where all affected rulesets should be verified) or after upgrading the firmware of the

Engineer access level is required.

During this test, all field device inputs will be ignored by the TPPR. The Cause and Effect matrix will not be evaluated. No outputs will be generated.

The purpose of this test is to check that input channels are configured correctly, including alarm, warning, fault thresholds etc. The gas concentration and alarm states raised by forcing the input value can be viewed on the TPPR UI or the PC GUI. All configured rules should be tested to ensure the logic in the controller is correct. The system fault relay will be open.

How to use the Configuration Settings Test Mode:

- 1. Login as an Engineer.
- From the **System Status** screen select the **Tool Box** icon:



Select Diagnostics.

- 4. Select the Menu icon:
- 5. Select Configuration Settings Test.
- The system will ask you to confirm; select Yes to proceed.
- The system will display a confirmation message, click on **OK** and you will be automatically navigated to the **Inputs** 7.
- Select the channel to be tested and select Input Details from the popup menu.
- 9. From the Input Details screen, select the Menu icon: 🛂



- 10. Select Force Value.
- 11. Enter the gas concentration that you want to simulate. This can include over and under range values.
- 12. The system will return to the Input Details screen, where it will show the simulated gas value as well as any corresponding active events (e.g. Alarm 1).
- 13. When ready, select the **Menu** icon:



- 14. Select Clear Force.
- 15. Repeat steps 9 14 as required, completing the channel tests.
- 16. Return to the **Inputs** screen and repeat steps 8 14 for the next channel.
- 17. When the test is complete, go to the **System Status** screen and select the **Tool Box** icon:



- 18. Select Diagnostics.
- 19. Select the **Menu** icon: **W**
- 20. Select Stop Configuration Settings Test.
- 21. The system will show a confirmation message that it has returned to normal operation.



WARNING



3.2.3 Cause and effect tests

This proof test should be run following initial commissioning, after the required periodic interval as well as after any modification to the configured rules (where all affected rulesets should be verified) or after upgrading the CCB firmware.

Engineer access level is required.

During this test, all field device inputs will be ignored by the TPPR system. The Cause and Effect matrix will be evaluated based on simulated input states and outputs will be generated. The system fault relay will be open.



WARNING

During the Cause and Effect Test, outputs will be generated and relays will be activated. To avoid any unwanted activation of output devices (e.g. emergency flooding) always inhibit or disable relay activated outputs before starting and remember to enable them when testing is finished.

This test has two purposes:

- To verify that Cause and Effect matrix configuration is correct by forcing the state of the input channels to various combinations. The activated/de-activated output channels corresponding to the forced state of input channels can be viewed on the TPPR UI or Webserver (if enabled).
- To check that the output channels are configured correctly, including delay on/off times etc. By forcing the state of the output channel to change the corresponding change in the output device state can be viewed on the TPPR UI or Webserver (if enabled).

When performing this proof test due to modifications made to the system only the modified portions must be re-tested.

This may be limited to test purpose 1 or 2 in this scenario depending on the modifications made.

How to use the Cause and Effect Test Mode:

- 1. Login as an Engineer.
- 2. From the **System Status** screen select the **Tool Box** icon:



- 3. Select Diagnostics.
- Select the Menu icon:
- Select Cause and Effect Test.
- The system will ask you to confirm, select Yes to proceed.
- The system will display a confirmation message, click on **OK** and you will be automatically navigated to the **Outputs** screen.
- 8. Select the channel to be tested and select **Output Details** from the popup menu.
- 9. Select the Menu icon: V



- 10. Select Force Input States to do a full test of the Cause and Effect matrix (test purpose1 described above).
- 11. The system will display a matrix of all the input channels that are linked to the output channel being tested.
- 12. Select the input channel states that you want to simulate, and click on Force. The cells corresponding to the forced states will be coloured.
- 13. The system will return to the **Outputs** screen where the results of the forced input states can be viewed.
- 14. When ready, return to the **Output Details** screen and select the **Menu** icon:



- 15. Select Clear Force.
- 16. Repeat steps 8 15 for the next channel.
- 17. To force the output relays (test purpose 2, described above) select the channel to be tested and select Output Details from the popup menu.
- 18. Select the Menu icon and select Force from the popup menu. The output will now be activated and the result can be verified.
- 19. When ready, select the channel again, and select Clear Force.
- 20. Repeat steps 17 19 for the next channel.
- 21. When the test is complete, qo to the System Status screen and select the Tool Box icon then Diagnostics.
- 22. Select the **Menu** icon: V



- 23. Select Stop Cause and Effect Test.
- 24. The system will show a confirmation message that it has returned to normal operation.



WARNING



3.3 AIM mA Proof Tests

Engineer access level is required.

During this test, all field device inputs will be displayed, but the **Cause and Effect** matrix will not be evaluated. No outputs will be generated.

The purpose of this test is to check that the input module correctly reports the expected input value. Typically, this can be done either by applying a test gas to the sensor in the field or by forcing the mA output of the sensor to a given value (if the sensor provides such a functionality). The gas concentration and alarm states raised for the channel can then be viewed on the Touchscreen UI or PC GUI. The system fault relay will be open.

The proof test should check that the input reads accurately (+/-10% of full scale value) for a given input value. A minimum of two points throughout the measurement range must be checked per input sensor (for instance, 4mA equating to 0% gas range and 12mA equating to 50% gas range).

How to use the Field Inputs Test mode:

- 1. Login as an Engineer.
- 2. From the System Status screen select the Tool Box icon:



Select Diagnostics.

- 4. Select the **Menu** icon:
- 5. Select Field Inputs Test.
- The system will ask you to confirm, select Yes to proceed.
- 7. The system will display a confirmation message, click on OK and you will be automatically navigated to the Active Events screen.
- 8. Proceed with the test of the field devices. To see more detailed information at any time, select the channel of interest and select Input Details from the popup menu.

Note: If the test is done from the **Active Events** screen, the channel of interest will be shown as soon as its state changes, i.e. a threshold alarm is generated. Alternatively, you may wish to work from the Inputs screen (return to System Status screen and select Inputs) by scrolling down to the channel you want.

9. When the test is complete, return to the System Status screen and select the Tool Box icon:



- 10. Select Diagnostics.
- 11. Select the **Menu** icon:



13. The system will show a confirmation message that it has returned to normal operation.



WARNING



3.4 AIM mV Proof Tests

Engineer access level is required.

During this test, all field device inputs will be displayed, but the Cause and Effect matrix will not be evaluated. No outputs will be generated.

The purpose of this test is to check that the input module correctly reports the expected input value. Typically, this can be done either by applying a test gas to the sensor in the field or by forcing the output of the sensor to a given value (if the sensor provides such a functionality). The gas concentration and alarm states raised for the channel can then be viewed on the Touchscreen UI or PC GUI. The system fault relay will be open.

The proof test should check that the input reads accurately (+/-10% of full scale value) for a given input value. A minimum of two points throughout the measurement range must be checked per input sensor (for instance, 0% gas range and 50% gas range).

How to use the Field Inputs Test mode:

- 14. Login as an Engineer.
- 15. From the **System Status** screen select the **Tool Box** icon:



- 16. Select Diagnostics.
- 17. Select the **Menu** icon:
- 18. Select Field Inputs Test.
- 19. The system will ask you to confirm, select Yes to proceed.
- 20. The system will display a confirmation message, click on OK and you will be automatically navigated to the Active Events screen.
- 21. Proceed with the test of the field devices. To see more detailed information at any time, select the channel of interest and select Input Details from the popup menu.

Note: If the test is done from the Active Events screen, the channel of interest will be shown as soon as its state changes, i.e. a threshold alarm is generated. Alternatively, you may wish to work from the Inputs screen (return to System Status screen and select Inputs) by scrolling down to the channel you want.

22. When the test is complete, return to the System Status screen and select the Tool Box icon:



- 23. Select Diagnostics.
- 24. Select the **Menu** icon: V
- 25. Select Stop Field Inputs Test.
- 26. The system will show a confirmation message that it has returned to normal operation.



WARNING



3.5 **DIM Proof Tests**

Engineer access level is required.

During this test, all field device inputs will be displayed, but the **Cause and Effect** matrix will not be evaluated. No outputs will be generated.

The purpose of this test is to check that the input module correctly reports the expected input value. Typically, this can be done either by applying a test gas to the sensor in the field or by forcing the output of the sensor to a given state. Both input open and input closed states should be checked. For digital inputs used for interaction signalling, the input switch can be used to indicate the two states.

How to use the Field Inputs Test mode:

- 27. Login as an Engineer.
- 28. From the **System Status** screen select the **Tool Box** icon:



- 29. Select Diagnostics.
- 30. Select the Menu icon:
- 31. Select Field Inputs Test.
- 32. The system will ask you to confirm, select Yes to proceed.
- 33. The system will display a confirmation message, click on OK and you will be automatically navigated to the Active Events screen.
- 34. Proceed with the test of the field devices. To see more detailed information at any time, select the channel of interest and select Input Details from the popup menu.

Note: If the test is done from the **Active Events** screen, the channel of interest will be shown as soon as its state changes, i.e. a threshold alarm is generated. Alternatively, you may wish to work from the Inputs screen (return to System Status screen and select Inputs) by scrolling down to the channel you want.

35. When the test is complete, return to the System Status screen and select the Tool Box icon:



- 36. Select Diagnostics.
- 37. Select the **Menu** icon: V
- 38. Select Stop Field Inputs Test.
- 39. The system will show a confirmation message that it has returned to normal operation.



WARNING



3.6 ROM Proof Tests

Visual inspection of the relay contact wiring should be undertaken to verify that the wiring conforms to the configurations detailed in section 2.2.4 of this document for relay outputs designed to be compliant to SIL 2. This should include inspection to verify that a suitable fuse is present to protect the relay contacts.

The below test method should be repeated for each relay contact. A multimeter or similar test instrument should be used to physically check the state of the contacts at various points through the proof test.

To test the Relay output channels by forcing the relays to a specific state:

- 1. Login as an **Engineer**. Navigate to the Outputs screen:
 - a) From the System Status screen select the Inputs icon:



- b) Toggle the Inputs Icon to select the **Outputs** icon:
- 2. Select the channel to be tested, and then select **Force** or **Force Deactivate**, as required. The channel will indicate a Fault until the action is cancelled.
- 3. When ready, select the channel again, and select **Clear Force** from the popup menu.
- 4. Repeat steps 4 and 5 for all relay output channels.

Note: The system will indicate a fault and the System Fault relay will open while a Force condition is present.



WARNING



4 Example Safety Chain Calculations

This chapter shows examples of how to calculate the PFD and PFH figures for a given safety chain. It provides guidance to the end user in correctly specifying the safety chains given the different configurations of the TPPR system. This section gives information only on some of the configurations that are possible, but the approach used can be extended to apply to the more complex configurations (1003 sensor voting etc) that are realisable with the TPPR system.

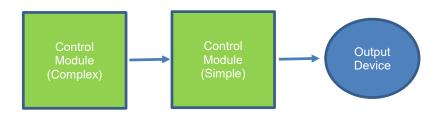
The figures quoted come from the table shown in section 2 of this document as well as excerpted tabular information from *IEC 61508-6*.

These figures represent the PFD and PFH for the Touchpoint Pro controller only. PFD and PFH values for the sensor and output device have to be added to complete the chain. The table below shows how Safety Integrity Level (SIL) is related to the likely frequency of occurrence over a nominal period, and gives probability figures for both low risk (PFD) and high risk (PFH) failures. This table repeats information given in IEC 61508-2.

Safety Integrity Level (SIL)	Low Demand (PFD)	High Demand (PFH)		
4	>10 ⁻⁵ to <10 ⁻⁴	>10 ⁻⁹ to <10 ⁻⁸		
3	>10 ⁻⁴ to <10 ⁻³	>10 ⁻⁸ to <10 ⁻⁷		
2	>10 ⁻³ to <10 ⁻²	>10 ⁻⁷ to <10 ⁻⁶		
1	>10 ⁻² to <10 ⁻¹	>10 ⁻⁶ to <10 ⁻⁵		



4.1 Example for System Fail or System Fault safety chain



The figure above shows the connection of the System Fail or System Fault relay output to a higher level system to inform that system of partial or full impairment of operation. The assumed application is a low demand (PFD) SIL 2 application with a proof test interval of one year for the Control Module and ten years for the relay output.

The elements of the chain can simply be added together (refer to the table in section 2 for numbers used):

Chain elements = Control Module (Complex) + Control Module (Simple)

PFD = $3.08 \times 10^{-4} + 1.46 \times 10^{-04} = 1.46 \times 10^{-4}$

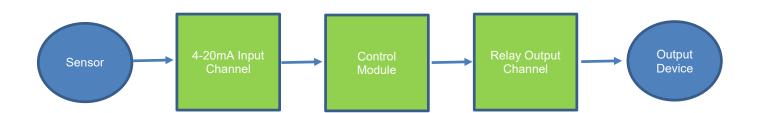
PFD = 1.46*10⁻⁴, which = 1.5% of the SIL 2 Budget

The same chain could also be assessed for high or continuous demand (uses the PFH figure). For that case the PFH figures for each element of the chain are added together (refer to the table in section 2 for numbers used):

PFH = $6.58 \times 10^{-8} + 3.76 \times 10^{-09} = 6.96 \times 10^{-8}$

PFH = 6.96*10⁻⁸, which = 7% of the SIL 2 Budget

4.2 Example for SIL 1 Applications



The figure above shows the use of one input and one output channel all in a 1001 configuration. The assumed application is a low demand (PFD) SIL 1 application with a proof test interval of one year.

It is assumed that the Sensor complies to use in a SIL 1 application, and consumes no more than 35% of the SIL 1 budget. Likewise, the Output Device is assumed to consume no more than 50% of the SIL 1 budget.

The elements of the chain can simply be added together (refer to the table in section 2 for numbers used):

Chain elements = 4-20mA Input Module + Control Module (Complex) + Relay Module (Complex) + Relay Module (Simple)

PFD = $1.91 \cdot 10^{-4} + 3.08 \cdot 10^{-4} + 1.48 \cdot 10^{-4} + 5.53 \cdot 10^{-4} = 1.2 \cdot 10^{-3}$

PFD = 1.2*10⁻³, which = 1.2% of the SIL 1 Budget

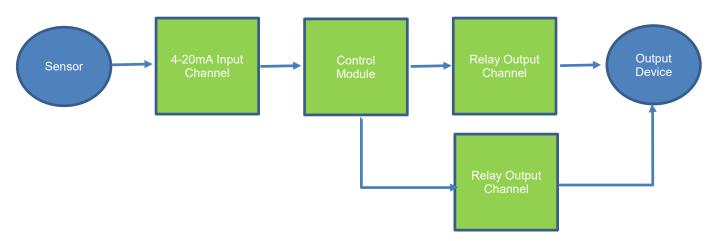
The same chain could also be assessed for high or continuous demand (uses the PFH figure). For that case the PFH figures for each element of the chain are added together (refer to the table in section 2 for numbers used):

PFH = $4.10 \cdot 10^{-8} + 6.58 \cdot 10^{-8} + 3.2 \cdot 10^{-8} + 1.26 \cdot 10^{-7} = 2.65 \cdot 10^{-7}$

PFH = 2.65*10⁻⁷, which = 2.7% of the SIL 1 Budget



4.3 Example for SIL 2 Applications



The figure above shows the use of one input (in a 1001 configuration) and two output channels in a 1002 configuration. The assumed application is a low demand (PFD) SIL 2 application with a proof test interval of one year. It is also assumed that the output channels come from the same I/O Module (taking the output channels from two independent I/O modules would reduce the PFD figures further).

It is assumed that the Sensor complies with use in a SIL 2 application, and consumes no more than 35% of the SIL 2 budget. Likewise, the Output Device is assumed to consume no more than 35% of the SIL 2 budget.

The contribution of the 1oo2 architecture of the relay output modules can be estimated using the tables in *IEC 61508-6* (see *Tables B.3 & B.4*).

From the table given in section 2 an appropriate figure can be determined for the use of the two relay contacts. For this example, we are assuming a proof test interval of 10 years, giving a PFD figure of 1.50·10⁻⁰⁴

The elements of the chain can now be added together (refer to the table in section 2 for numbers used):

Chain elements = 4-20mA Input Module + Control Module (Complex) + Relay Module (Complex) + 1oo2 redundant Relay Module (Simple)

PFD =
$$1.91 \cdot 10^{-4} + 3.08 \cdot 10^{-4} + 1.48 \cdot 10^{-4} + 1.50 \cdot 10^{-4} = 7.97 \cdot 10^{-4}$$

PFD = 7.97*10⁻⁴, which = 8% of the SIL 2 Budget

The same chain could also be assessed for high or continuous demand (using the PFH figure). For that case the PFH figures for the 1002 architecture of the relay output modules needs to be applied. These figures can be seen listed for various proof test intervals in the second table seen in section 2. For this example, we are assuming a proof test interval of 10 years, giving a PFH figure of $3.86 \cdot 10^{-09}$

The elements of the chain can now be added together (refer to the table in section 2 for numbers used):

PFH =
$$4.1 \cdot 10^{-8} + 6.58 \cdot 10^{-8} + 3.2 \cdot 10^{-8} + 3.86 \cdot 10^{-9} = 1.42 \cdot 10^{-7}$$

PFH = 1.42*10⁻⁷, which = 14% of the SIL 2 Budget

Note that this final example assumes that the two relay contacts reside on the same relay module. If two relay channels from different relay modules were used the redundancy effect of using two separate relay modules would reduce the PFH figure accordingly (the effect of this redundancy can be calculated by using the data in the first table in section 2 for the Relay Output Module (Complex) along with the relevant calculations from IEC 61508:2010).

These overall figures could be improved by reducing the proof test interval of the relay contacts which has the effect of decreasing the probability of failure.



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Issue 1_1/2017 2400M2568 A04948 © 2017 Honeywell Analytics